

QUAD/Y6/X8 TAROT GIMBAL



Tarot brushless gimbal with QUAD/Y6/X8 mounting plate



Three spacers



Three mounting screws

1 Attach camera

Your Tarot gimbal is compatible with a GoPro HERO3, available from store.3dr.com.



Important note: Make sure that the WiFi on your GoPro is turned **OFF** at all times when in use with your aircraft.

1 Remove the two screws securing the blue face plate. Remove the plate, and loosen the set screw.



2 Slide camera into housing with the lens nearest the top-right corner.



Place the blue face plate over the camera, and secure from the back with the two original screws.



2 Connect

Locate the black and white two-wire cables protruding from the bottom of your copter and from the top of the gimbal. Connect the cables together by attaching the black connectors.



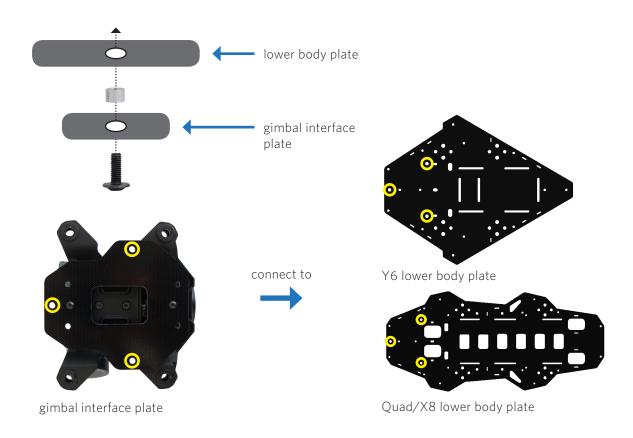
3 Power

Connect the gimbal power cable with the red, JST connector to the matching red, JST connector on the copter.



4 Mount

To mount the gimbal to your copter, add a mounting screw from below the gimbal to each of the three holes in the gimbal interface plate indicated below. Add a spacer to each screw above the gimbal plate, and attach the screws to the three holes in the lower body plate indicated below. The spacers should be **between the gimbal interface plate and the lower body plate**.

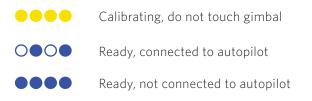


Operating the gimbal

Start your flight by following the preflight steps described in your copter's manual and checklist.

Upon powering your copter, the gimbal will display a solid yellow light while it is starting and calibrating. **Do not touch the gimbal while it is starting up.** When the gimbal displays a blinking blue light, it is ready to fly.

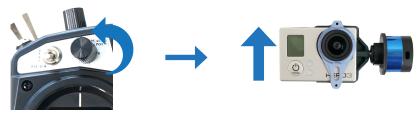
If the gimbal is not connected to the autopilot, it will perform automatic stabilization without enabled transmitter control, indicated by a solid blue light.



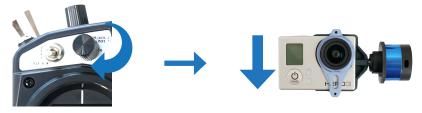
If you connected the gimbal to Pixhawk, use the knob shown below on the RC transmitter to control the tilt of the camera in flight.



Rotate counterclockwise to tilt the camera up.



Rotate clockwise to tilt the camera down.



Configuring gimbal control for non-3DR RC systems

To calibrate a non-3DR transmitter to control the Tarot gimbal, you will need to enable channel six for a knob on your transmitter during RC calibration in the mission planner application. Once channel six is enabled, the preconfigured Pixhawk settings will automatically assign gimbal control to the selected control knob on the transmitter.

If you are using a PPM encoder to connect to Pixhawk, you will need to connect channel six from your RC receiver to the encoder before calibration.

Configuring the gimbal

Tarot gimbals from 3DR arrive preconfigured and ready to fly. For information on changing the gimbal configuration and updating the gimbal software, <u>visit the wiki page here</u>.

Support

For customer support, contact us at **help@3dr.com** or call our support line at **+1 (858) 225-1414** Monday through Friday, from 8 am to 5 pm, PST.

